



## Study on fixed points for occasionally weakly compatible in symmetric spaces

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**Abstract:** In this paper, we obtain a unique common fixed point theorem for OWC(Occasionally Weakly Compatible) four self- mappings in symmetric spaces. This result is a generalization, improving, extending, known comparable results existing in the literature.

**Key words:** Common fixed point theorem, OWC(Occasionally Weakly Compatible), Symmetric space.

**AMS Subject Classifications:** 47H10, 54H25.

### 1. Introduction

We know that Banach contraction principle (prior to 1968) is a fundamental result in fixed point theory. Later on Kannan [14] obtained a fixed point result for a mapping satisfying contractive condition that need not satisfy continuity. Subsequently many authors has been extended and improved and generalizes these result in many ways (see for e.g. [1-13] and [15-18]). Hicks and Rhoades [10] obtained some common fixed point theorems in symmetric spaces and semi metric spaces. Recently, Abbas and Rhoades [6] obtained some common fixed point results for occasionally weakly compatible mappings satisfying a generalized contractive condition in symmetric spaces. In this paper we obtained a common fixed point theorem for OWC(Occasionally Weakly Compatible) four self- mappings in symmetric spaces. Our results are more general than the several well known results.

#### 1.1. Preliminaries

The following are useful in our main results which are due to [6].

**Definition 1.1.** Two maps  $p$  and  $q$  are said to be weakly compatible if they commute at coincidence points.

**Definition 1.2.** Let  $X$  be a set ,  $p, q$  self maps of  $X$ . A point  $x$  in  $X$  is called a coincidence point of  $p$  and  $q$  iff  $px = qx$  . We shall call  $w = px = qx$  a point of coincidence of  $p$  and  $q$ .

**Definition 1.3.** Two self maps  $p, q$  of a set  $X$ . A point  $x$  in  $X$  are said to be OWC(Occasionally Weakly Compatible) iff there exists a point  $x$  in  $X$  which is a coincidence point of  $p$  and  $q$  at which  $p$  and  $q$  are commute.

**Lemma 1.1** (11). *Let  $X$  be a set ,  $p, q$  are OWC(Occasionally Weakly Compatible) self maps of  $X$ . If  $p$  and  $q$  have a unique point coincidence  $w = px = qx$  , then  $w$  is a unique common fixed point of  $p$  and  $q$ .*

Our results are proved in symmetric spaces, which are more general than metric spaces.

**Definition 1.4.** Let  $X$  be a set. A symmetric on  $X$  is a mapping  $\rho(x, y) : X \times X \rightarrow [0, \infty)$  such that  $\rho(x, y) = 0$  if and only if  $x = y$ , and  $\rho(x, y) = \rho(y, x)$  for  $x, y \in X$ .

Let  $A \in [0, \infty)$ ,  $R_A^+ = [0, A)$ . Let  $F : R_A^+ \rightarrow R$  satisfy

(i).  $F(0) = 0$  and  $F(t) > 0$  for each  $t \in (0, A)$  and (ii).  $F$  is non decreasing on  $R_A^+$ .

Define,  $F[0, A) = \{F : R_A^+ \rightarrow R : F \text{ satisfies (i) - (ii)}\}$ . Let  $A \in [0, \infty)$ . Let  $\Psi : R_A^+ \rightarrow R$  satisfies (i).  $\Psi(t) < t$  for each  $t \in (0, A)$  and (ii).  $\Psi$  is non decreasing.

Define,  $\Psi[0, A) = \{\Psi : R_A^+ \rightarrow R : \Psi \text{ satisfies (i) - (ii) above}\}$ .

Some of the examples of mappings  $F : R_A^+ \rightarrow R : F$  satisfies (i) - (ii), we have refer to [17].

**Definition 1.5.** A control function  $\Phi$  defined by  $\Phi : R^+ \rightarrow R^+$  which satisfies  $\Phi(t) = 0$  if and only if  $t = 0$ .

## 2. Main Results

In this section, we proved a unique common fixed point theorem for four self-mappings for OWC(Occasionally Weakly Compatible) mappings in symmetric spaces.

Now we prove our main theorem.

**Theorem 2.1.** Let  $X$  be a set,  $\rho$  a symmetric on  $X$ . Let  $M, N, S$  and  $T$  be four self-mappings of  $X$  satisfying the following conditions:

$$F(\Phi(\rho(Mu, Nv))) < \Psi(F(K_\Phi(u, v))), \quad (1)$$

where,

$$K_\Phi(u, v) = \text{Max}\{\lambda_1[\Phi(\rho((Mu, Tv)) + \Phi(\rho(Su, Mu)) + \Phi(\rho(Nv, Tv)))] + \text{Max}\{\lambda_2[\Phi(\rho(Mu, Tv)) + \Phi(\rho(\frac{Su, Nv}{2}))]\}\}.$$

Where,  $\lambda_1, \lambda_2 > 0$  and  $\lambda_1 + \lambda_2 < 1$ .

For each  $u, v \in X$ ,  $F \in F[0, B)$  and  $\Psi \in \Psi[0, F((B - 0))$ , where  $B = D$  if  $D = \infty$  and  $B > D$  if  $D < \infty$ . And

$$(M, S) \text{ and } (N, T) \text{ are OWC.} \quad (2)$$

Then  $M, N, S$  and  $T$  are having a unique common fixed point in  $X$ .

*Proof.* Given by (2)  $(M, S)$  and  $(N, T)$  are OWC, then there exists two points  $u, v \in X$  such that  $Mu = Su$  and  $Nv = Tv$ . For suppose that  $Mu \neq Nv$ . Then from (1) we get that,

$$\begin{aligned} K_\Phi(u, v) &= \text{Max}\{\lambda_1[\Phi(\rho((Mu, Nv)) + \Phi(\rho(Mu, Mu)) + \Phi(\rho(Tv, Tv)))] + \text{Max}\{\lambda_2[\Phi(\rho(Mu, Nv)) + \Phi(\rho(\frac{Mu, Nv}{2}))]\}\}, \\ &= \text{Max}\{\lambda_1[\Phi(\rho((Mu, Nv)) + \Phi(\rho(0)) + \Phi(\rho(0)))] + \text{Max}\{\lambda_2[\Phi(\rho(Mu, Nv)) + \Phi(\rho(\frac{Mu, Nv}{2}))]\}\}, \\ &= \text{Max}\{\lambda_1[\Phi(\rho((Mu, Nv)))] + \text{Max}\{\lambda_2[\Phi(\rho(Mu, Nv))]\}\}, \\ &= \lambda_1[\Phi(\rho((Mu, Nv)))] + \lambda_2[\Phi(\rho(Mu, Nv))], \\ &= (\lambda_1 + \lambda_2)[\Phi(\rho((Mu, Nv)))] \text{, (since } \lambda_1 + \lambda_2 < 1) \end{aligned}$$

$$< \Phi(\rho(Mu, Nv)). \quad (3)$$

Then from (1) and (3) we get that ,

$$\begin{aligned} 0 < F(\Phi(\rho(Mu, Nv))) &< \Psi(F(K_{\Phi}(u, v))) \\ &< \Psi(F(\Phi(\rho(Mu, Nv))), \\ &< F(\Phi(\rho(Mu, Nv))), \text{ which is a contradiction.} \end{aligned}$$

Therefore,  $\Phi(\rho(Mu, Nv)) = 0$ .

$$\implies \rho(Mu, Nv) = 0.$$

$$\implies Mu = Nv. \text{ That is, } Mu = Su = Nv = Tv.$$

Suppose that if there exists another point  $z$  such that  $Mz = Sz$ , then using (1) and (3) we get that  $Mz = Sz = Nv = Tv = Mu = Su$  or  $Mu = Mz$  and  $w = Mu = Su$  is the unique point of  $M$  and  $S$ . By Lemma (1.1) ,  $w$  is the only common fixed point of  $M$  and  $S$ . By symmetry there exists a unique point  $z \in X$  such that  $z = Nz = Tz$ . Suppose that  $w \neq z$  then by (1) and (3) we get that,

$$\begin{aligned} F(\Phi(\rho(w, z))) = F(\Phi(\rho(Mw, Nz))) &< \Psi(F(K_{\Phi}(w, z))) \\ &< \Psi(F(\Phi(\rho(w, z)))) \\ &< F(\Phi(\rho(w, z))), \text{ which is a contradiction.} \end{aligned}$$

Therefore,  $\Phi(\rho(w, z)) = 0$ .

$$\implies \rho(w, z) = 0.$$

$$\implies w = z.$$

Therefore,  $w = z$  is a common fixed point. By the preceding argument and it is clear that  $w$  is the unique. Therefore,  $M$ ,  $N$ ,  $S$  and  $T$  are having a unique common fixed point in  $X$ . And this completes the proof of the theorem.  $\square$

### 3. Conclusion

Our results are more general than the results of [6].

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